First Year Report

Loïc Fejoz

March 2, 2007

Contents

1	Introduction	1
2	Related work	2
	2.1 Lock-free libraries and algorithms	2
	2.2 Basic notions	2
3	My Work	3
	3.1 Introduction	3
	3.2 Assume-Guarantee in Isabelle	4
	3.3 B method	4
	3.4 TLA^+ and ^+CAL	5
4	Future work and conclusion	5
5	Courses	6
	5.1 $TiC06$	6
	5.2 Models and multi-agents system	6
A	B Machines	6
В	Concrete Syntax	10
С	Assignment	12
	C.1 Atomic assignment	12
	C.2 Atomic assignment with CAS	12
D	Bibliography	15

1 Introduction

One year ago my project proposal was to apply well-known methods in my research team to lock-free algorithms. Those methods are B, TLA^+ and

model-checking. Those methods imply a top-down approach. So the idea was to develop new algorithms. Since then I discovered a lot of algorithms and a lot of work on developing such algorithms. But proofs were very rare and none of them were written within a proof-assistant. Therefore, I want to justify lock-free algorithms by applying well-known methods, and in particular B and TLA^+ .

In this report, I will first introduce lock-free algorithms and their properties. I will also present methods that should be useful for proving algorithms. Then I will expose my preliminary work with those methods. I will end with suggestions for an easier method to use for proving the correctness of lock-free algorithms.

2 Related work

2.1 Lock-free libraries and algorithms

Usually algorithms that manage a shared data structure use locks. Lockfree algorithms are designed such that they allow multiple processes (a.k.a. threads) to access the shared data structure concurrently, either for reading or writing. Instead of central locking, these algorithms rely on particular atomic primitives. It solve problems like deadlock and priority inversion. Depending on the contention it can also be more efficient. Those new algorithms are possible because hardwares now provide some complex atomic primitives.

A lot of work as been done in the last three years. It starts from research articles about algorithms (with justifications) [16, 7, 17, 12], to fully useable libraries [3, 12, 1]. In between we can find stand-alone algorithms [11, 2, 4].

Another interesting project is Software Transaction Memory [5]. It is partially related to lock-free algorithms. Indeed it provides programmers with a high-level view of transaction. In the background (implementation) it is based on lock-free algorithms. It would be nice for the target method to be able to prove those implementations.

2.2 Basic notions

Actually a data-structure is not changed by a single algorithm but by several. For instance, on a list you will find an algorithm for appending an element, one for retrieving while deleting elements, and one for inserting. Those algorithms can be run concurrently by several process.

When reasoning about a data-structure, it helps if all methods appear to be executed atomically. This property is called linearisability [10]. A concurrent execution trace is linearisable iff there exists a sequential execution trace that has the same externally observable behaviour. x = f(x);

Figure 1: A non-implementable assignment

Usually locks are replaced by loops that use atomic primitives provided by the processor (like the CAS_1 presented in section 3.1). So we can wonder about termination. This leads to the following definition. I have not focused yet on liveness properties and termination problem.

wait-free All threads make progress even if others incur delays;

lock-free Some thread always makes progress;

obstruction-free guarantees progress for any thread that eventually executes in isolation.

3 My Work

3.1 Introduction

During the first year of the thesis, my work was around the use of Compareand-Swap (a.k.a. CAS). CAS_1 is an atomic operation that can be found on modern processors. It is also known as a universal constructor for atomic operations [9]. CAS_1 is equivalent to the atomic execution of:

```
word_t CAS1(word_t *a, word_t o, word_t n) {
    old = *a;
    if (old == o) {
        *a = n;
     }
    return old;
}
```

I will sometimes use an operation called $BCAS_1$. It is similar to CAS_1 but returns TRUE if the reference cell was updated and FALSE otherwise.

In this section I will present my preliminary experiences with proving a very simple concurrent algorithm. But one must keep in mind that my goal is to prove algorithms from [8]. There is a set of patterns used by Lock-free algorithms. This is were the following pattern comes from.

The pattern is simply replacing one assignment of the type shown in figure 1 by the program shown in figure 2, where f is a pure function (*i.e.* it has no side effects).

I want to prove that the latter could substitute the former. But to do so I need to tell in which environment the algorithm is used. Following the

```
b = false;
do {
    v = x;
    fv = f(v);
    b = BCAS1(x, v, fv);
} while(!b);
```

Figure 2: Assignment with $BCAS_1$

assume-guarantee method, I want to compose the algorithm with another process that can assign any value (respecting the type) to x.

In the following sections I will explain my attempts to prove this algorithm in different languages. Some of them are supported by tools.

3.2 Assume-Guarantee in Isabelle

A rely-guarantee tuple $\langle rely, guarantee \rangle \{\phi\} P\{\psi\}$ is pretty much like a Hoare triple but it adds two predicates: *rely* that expresses what this program *P* relies on from the other programs to be correct, and *guarantee* that expresses what this part *P* guarantees to the other. This logic [14] has been encoded in Isabelle [15].

One part of proving the assignment example is to show that the tuple $\langle b' = b \land fv' = fv \land v' = v, x' = x \lor x' = f(x) \rangle \{\top\} P\{\top\}$ holds (*P* being the program on figure 2). The first step was to modify the language to add $BCAS_1$ in the primitive language (defined in appendix A). The proof is given in appendix A.

The proof is only a partial one as we have not proved that the assignment is done only once. For that purpose we could have added some ghost variable that counts how many time we are doing the assignment. The post-condition would then assert that the counter equals one.

This framework does not suit well our purpose because:

- 1. you need extra variables;
- 2. it does not permit to develop a family of algorithms;
- 3. the proof is messed up with encoding details;

3.3 B method

The simplest way to reason about concurrent program is by using invariants. It is one of the main ideas of the B method besides refinement. The B method was elaborated by Jean-Raymond Abrial [6]. It is a well-established method and several tools exist to prove refinements. Indeed the method describes a system by a set of events. Then you can refine a specification by either adding concrete events or by adding data refinement.

Appendix A presents a simple B machine M0 that just defines a system where two kinds of events can happen, either the guarantee or the rely event. Then we derive two refinement machines. The first one, M1 (on page 8), explicitly introduces the concrete operations, and the second one, M2 (on page 8), adds flow control with a place predicate.

The B method can help us to co-develop several algorithms but it does not ease the reading of the invariant by not allowing local invariants. Also refinement needs to be done on a per event basis, that is why in the most abstract specification M0 (on page 6), the action *guar* appears several times. Making several (clever) refinements helps the proofs to be done automatically; otherwise interactive proofs would have been necessary.

3.4 TLA^+ and +CAL

I wrote similar specifications as the previous ones but with TLA^+ . Unfortunately, TLA^+ only comes with a model-checker. But Lamport has defined an interesting language called +CAL [13]. +CAL is an algorithm language. It is meant to replace pseudo-code for writing high-level descriptions of algorithms. +CAL specifications are then translated into TLA^+ .

 ^+CAL and TLA^+ could have been well-suited for our problem provided that you could choose the granularity of statements and that a prover existed. The notation is powerful and elegant. Also one good point is that you do not need to express which event refines which one, *i.e.* it does not ask for a linearisability point as B does.

4 Future work and conclusion

It was very insightful and interesting to try to prove such a simple algorithm with those different methods. It let me discover their strengths and weaknesses towards our problem.

So a well-suited method for our problem should allow

- to jointly develop several algorithms,
- to refine from an atomic specification to a lock-free one,
- to compose several specifications,
- to express linearisability points only when needed,
- one algorithm to do job in advance for another one another common pattern in lock-free algorithms —,
- not to use explicit place predicates.

I have recently started to define such a method and I will further develop it in the comming months. I will then use it to prive at least the RDCSS algorithm.

5 Courses

5.1 TiC06

In July, I attended the summer school TiC. TiC stands for Trends in Concurrency. The goal of the school was to expose graduate students and young researchers to new ideas in concurrent programming from experts in academia and industry. The school was organised at the Centro Residenziale Universitario of the University of Bologna, situated in Bertinoro. More details can be found at http://www.cs.purdue.edu/homes/jv/events/TiC06/.

Several courses where directly useful for my subject. The most notable one was "Highly Concurrent Data Structures" by Maurice Herlihy. Indeed he presented an algorithm for set that uses a lock-free list. It would be nice to prove its correctness. There were also courses about memory models and process algebras. It was also interesting to meet people to whom state your problem, do some tools demo and get some tips and ideas.

5.2 Models and multi-agents system

This course was part of my local obligation from the PhD program in Nancy. It is not strictly related to my topics as it presented concepts for multiagents system and their building. It then focused on reactive multi-agents for simulating complex phenomena. Finally it presented a cognitive model of agents. More details can be found at http://fst.uhp-nancy.fr/details/ form_ue/form_ue_MAIF3U22.html. But it was interesting to consider their problems, especially how to link (and prove?) the global system behaviour towards the local agent's behaviour.

A B Machines

```
MODEL

M0

/* This is a simple modelisation of the following RG Tuple:

<b:=b & v:=v & fv:=fv & x:: INTEGER, x:=f(x) or x:=x>{TRUE}x:=f(x){TRUE} */

VARIABLES

x, b, fv, v

CONSTANTS

f

PROPERTIES

f : INTEGER --> INTEGER

INVARIANT
```

```
x : INTEGER &
   b : BOOL &
   v : INTEGER &
  fv : INTEGER
INITIALISATION
  x :: INTEGER ||
  b :: BOOL ||
  v :: INTEGER ||
  fv :: INTEGER
EVENTS
/* This algorithm rely on the other to not change his local
variables but they can modify x */
   rely = BEGIN
       b := b ||
       v := v ||
       fv := fv \mid \mid
       \mathbf{x} :: INTEGER
   END;
   guar1a = BEGIN
       x\,:=\,x\,\mid\,\mid
       b :: BOOL ||
       v :: INTEGER ||
       fv :: INTEGER
   END;
   {\rm guar1b}\,=\,{\bf BEGIN}
       x := x \mid \mid
       b :: BOOL ||
       v :: INTEGER ||
       \mathrm{fv}\,::\,\mathrm{INTEGER}
   END;
   guar1c = BEGIN
       \mathbf{x} := \mathbf{x} \mid \mid
       b :: BOOL ||
       v :: INTEGER ||
       \mathrm{fv}\,::\,\mathrm{INTEGER}
   END;
   guar1d = BEGIN
       x\,:=\,x\,\left|\,\right|
       b :: BOOL ||
       v :: INTEGER ||
       fv :: INTEGER
   END;
/* This is the real event that does the assignment */
   {\rm guar2d}\,=\,{\bf BEGIN}
       x := f(x) \mid \mid
       b :: BOOL ||
       v :: INTEGER ||
       \mathbf{fv}\,::\,\mathbf{INTEGER}
   END
```

```
20
```

30

40

50

60

END

REFINEMENT M1/* Here w begin to replace the guarante by what the algorithm will do but without any order yet.*/ REFINES M0VARIABLES x, b, fv, v INITIALISATION x :: INTEGER || 10b :: BOOL || v :: INTEGER || fv :: INTEGER EVENTS guar1a = BEGINb := FALSEEND; guar1b = BEGIN20v := xEND; guar1c = BEGINfv := f(v)END; guar1d = SELECT (x /= v) THEN $\mathbf{x} := \mathbf{x} \mid \mid$ b := FALSEEND; 30 /* The test x=v if the one that will be done by the CAS operation. The second condition is necessary yet but will be remove in the next refinement. It correspond to a local invariant in the original algorithm. */ guar2d = SELECT x = v & fv = f(v)THEN $\mathbf{x} := \mathbf{f}\mathbf{v} \mid \mid$ b := TRUE

END END

REFINEMENT

M2 /* This is the concrete algorithm. We must have added the place predicate pc (aka program counter) and the correspondant labels lbl. We have then prove that x := f(v)can be replace by

b := FALSE; $do \ \{$ 10v := x;fv := f(v); $b := BCAS_1(x, v, fv)$ } while (not b) */ REFINES M1SETS $lbl = \{PCA, PCB, PCC, PCD, PCE\}$ VARIABLES 20x, b, fv, v, pc INVARIANT pc : lbl & ((pc = PCD) => (fv = f(v))) /* Here is the local invariant that was placed on the guard in the previous refinem INITIALISATION x :: INTEGER || b :: BOOL ||v :: INTEGER ||fv :: INTEGER || pc := PCA30 EVENTS guar1a = **SELECT** pc = PCA **THEN** b := FALSE ||pc := PCBEND; guar1b = SELECT pc = PCB THEN $\mathbf{v} := \mathbf{x} \mid \mid$ pc := PCCEND; 40 guar1c = SELECT pc = PCC THENfv := f(v) ||pc := PCDEND; /* In that case the CAS test fails. $b := CAS_1(x, v, fv)^*/$ guar1d = **SELECT** pc = PCD & x = v **THEN** $x := x \mid \mid$ $b := FALSE \mid \mid$ 50pc := PCBEND; /* The CAS operation is done. $b := BCAS_1(x, v, fv)^*/$ guar2d = **SELECT** pc = PCD & x = v **THEN** $x\,:=\,fv\,\mid\,\mid\,$ b := TRUE ||pc := PCEEND 60 END

B Concrete Syntax

```
theory RG_Syntax
```

imports "~~/src/HOL/HoareParallel/RG_Hoare" "~~/src/HOL/HoareParallel/Quote_Antiquote"
begin

```
syntax
```

("(`_ :=/ "_Assign" :: "idt \Rightarrow 'b \Rightarrow 'a com" _)" [70, 65] 61) "_skip" :: "'a com" ("SKIP") "_Seq" :: "'a com \Rightarrow 'a com \Rightarrow 'a com" ("(_;;/_)" [60,61] 60) "_Cond" :: "'a bexp \Rightarrow 'a com \Rightarrow 'a com" ("(OIF _/ THEN _/ ELSE _/FI)" [0, 0, 0] 61) "_Cond2" :: "'a bexp \Rightarrow 'a com \Rightarrow 'a com" ("(OIF _ THEN _ FI)" [0,0] 56) "_While" :: "'a bexp \Rightarrow 'a com \Rightarrow 'a com" ("(OWHILE _ /DO _ /OD)" [0, 0] 61) "_Await" :: "'a bexp \Rightarrow 'a com \Rightarrow 'a com" ("(OAWAIT _ /THEN /_ /END)" [0,0] 61) "_Atom" :: "'a com \Rightarrow 'a com" $("(\langle _{-} \rangle)" 61)$ "_Wait" :: "'a bexp \Rightarrow 'a com" ("(OWAIT _ END)" 61) :: "idt \Rightarrow 'b \Rightarrow 'b \Rightarrow 'a com" "_Cas" ("(CAS ´_, _, _ SAC)" [70, 65, 65] 61) "_Cas2" :: "idt \Rightarrow idt \Rightarrow 'b \Rightarrow 'b \Rightarrow 'a com" ("(`_ := CAS '_, _, _ SAC)" [71, 71, 65, 65] 61) ("(´_ := "_CasB" :: "idt \Rightarrow idt \Rightarrow 'b \Rightarrow 'b \Rightarrow 'a com" BCAS `_, _, _ SACB)" [71, 71, 65, 65] 61)

translations

```
"` x := a" \rightarrow "Basic «` (_update_name x a)»"

"SKIP" \rightleftharpoons "Basic id"

"c1;; c2" \rightleftharpoons "Seq c1 c2"

"IF b THEN c1 ELSE c2 FI" \rightarrow "Cond .{b}. c1 c2"

"IF b THEN c FI" \rightleftharpoons "IF b THEN c ELSE SKIP FI"

"WHILE b DO c OD" \rightarrow "While .{b}. c"

"AWAIT b THEN c END" \rightleftharpoons "Await .{b}. c"

"AWAIT b THEN c END" \rightleftharpoons "AWAIT True THEN c END"

"WAIT b END" \rightleftharpoons "AWAIT b THEN SKIP END"

"CAS `x, a, n SAC" \rightarrow "(IF `x=a THEN `x:=n FI)"

"`r := BCAS `x, a, n SACB" \rightarrow "((IF `x=a THEN `x:=n;; `r:=(1::nat))

ELSE `r:=(0::nat) FI))"
```

nonterminals

prgs

syntax

```
      "_PAR"
      :: "prgs \Rightarrow 'a"
      ("COBEGIN//_//COEND" 60)

      "_prg"
      :: "'a \Rightarrow prgs"
      ("_ " 57)

      "_prgs"
      :: "['a, prgs] \Rightarrow prgs"
      ("_//|//_" [60,57] 57)
```

translations

"_prg a" → "[a]" "_prgs a ps" → "a # ps" "_PAR ps" → "ps"

syntax

"_prg_scheme" :: "['a, 'a, 'a] \Rightarrow prgs" ("SCHEME [_ \leq _ < _] _" [0,0,0,60] 57)

translations

"_prg_scheme j i k c" \Rightarrow "(map (λ i. c) [j..<k])"

Translations for variables before and after a transition:

syntax

"_before" :: "id \Rightarrow 'a" ("°_") "_after" :: "id \Rightarrow 'a" ("^a")

translations

 $\begin{array}{cccc} "^{\mathrm{o}}x" \equiv T x & \text{`fst"} \\ "^{\mathrm{a}}x" \equiv T x & \text{`snd"} \end{array}$

$print_translation$ {*

```
val assert_tr' = quote_tr' (Syntax.const "_Assert");
```

```
fun bexp_tr' name ((Const ("Collect", _) $ t) :: ts) =
    quote_tr' (Syntax.const name) (t :: ts)
    bexp_tr' _ _ = raise Match;
```

```
fun upd_tr' (x_upd, T) =
  (case try (unsuffix RecordPackage.updateN) x_upd of
    SOME x => (x, if T = dummyT then T else Term.domain_type T)
    NONE => raise Match);
```

 \mathbf{end}

C Assignment

```
theory RG_Assign imports RG_Syntax begin
```

lemmas definitions [simp]= stable_def Pre_def Rely_def Guar_def Post_def
Com_def

C.1 Atomic assignement

```
record AtomicAssign =
  x :: nat
lemma AtomicAssign:
shows "\vdash `x := f `x sat [{ True } ,{ True } ,{ ax=f ^ox \lor ^ax=^ox } ,{
True } ]"
proof (rule Basic)
  show "{True} \subseteq { (AtomicAssign.x_update (f AtomicAssign.x)) \in {True} "
    by auto
  \mathbf{next}
    show "stable {True} {True} "
      by auto
  \mathbf{next}
    show "stable {True} {True} "
       by auto
  \mathbf{next}
    show "{(s, t). s \in {True} \land (t = s(AtomicAssign.x := f (AtomicAssign.x))
s) | \lor t = s) \} \subseteq \{ a_x = f \circ_x \lor a_x = \circ_x \} "
      by (simp, auto)
qed
```

C.2 Atomic assignement with CAS

```
record AssignWithCAS =
   x :: nat
   v :: nat
   fv :: nat
   b :: nat
```

```
lemma AssignWithCAS:
    shows "\- `b := (0::nat);; WHILE `b = (0::nat) DO `v := `x;; `fv :=
f ´v;; ´b := BCAS ´x, ´v, ´fv SACB OD sat [{ True } , {av=^{\circ}v \land ab=^{\circ}b}
\wedge {}^{\rm a}fv = {}^{\rm o}fv , {* {}^{\rm a}x = {}^{\rm o}x \vee {}^{\rm a}x = f {}^{\rm o}x , { True } ]"
proof (rule_tac mid="\{ b = 0 \}" in Seq)
    show "\vdash 'b := 0 sat [{ True } , {^av=^ov \land {^ab=^ob} \land {^afv=^ofv}} , {^ax=^ox}
\vee {}^{a}x=f {}^{o}x }, { `b = 0 } ]"
        by (rule Basic, auto)
next
    show "\vdash WHILE 'b = (0::nat) DO 'v := 'x;; 'fv := f 'v;; 'b := BCAS
`x, `v, `fv SACB OD sat [{ `b = 0 } , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 , a = 0 
\vee a_x = f o_x , [ True ]]"
    proof (rule_tac pre'="{ True }" and
              guar'=" \{ ax=ax \lor ax=f ax \} " and
              rely'=" {av=^{\circ}v \land ab=^{\circ}b \land afv=^{\circ}fv } " and
              post'="{ True }" in Conseq)
         show "{ b = 0 } \subseteq { True }"
             by auto
    next
         show "\{ av = av \land ab = ab \land afv = afv \} \subseteq \{ av = av \land ab = av \land afv \}
= ^{\circ} fv \}''
             by auto
    \mathbf{next}
         show "\{ ax = ax \lor ax = f ax = f x \} \subseteq \{ ax = ax \lor ax = f x \}"
              by auto
    \mathbf{next}
         show "{True} \subseteq {True}"
             by auto
    \mathbf{next}
         show "\vdash WHILE `b = 0 DO `v := `x;; `fv := f `v;; `b := BCAS `x,
'v, 'fv SACB OD sat [{ True }, av=ov \land ab=ob \land afv=ofv}, ax=ox \lor ax=f
<sup>o</sup>x} ,{ True }]"
         proof (rule While)
             show "stable {True} {av = ^{\circ}v \land ^{a}b = ^{\circ}b \land ^{a}fv = ^{\circ}fv}"
                   by auto
         \mathbf{next}
              show "{True} \cap - { [b = 0] \subseteq {True} "
                   by auto
         \mathbf{next}
              show "stable {True} {av = ^{\circ}v \land ^{a}b = ^{\circ}b \land ^{a}fv = ^{\circ}fv}"
                  by auto
         next
              show "\forall s. (s, s) \in \{ ax = ax \lor ax = f \circ x \} "
                  by auto
         \mathbf{next}
              show "\vdash 'v := 'x;; 'fv := f 'v;; (IF 'x = 'v THEN 'x := 'fv;;
 'b := 1 ELSE 'b := 0 FI sat [{True} \cap {'b = 0}, {av = \circ v \land ab = \circ b
```

 $\wedge {}^{a}fv = {}^{o}fv$, $\{\!\{^{a}x = {}^{o}x \lor {}^{a}x = f {}^{o}x\}\!\}$, $\{\!\{True\}\!\}\!\}''$ proof (rule_tac pre'=" $\{ b = 0 \}$ " and guar'="{ $a_x=o_x \vee a_x=f \circ x$ }" and rely'=" ${a v = ^{\circ} v \land ^{a} b = ^{\circ} b \land ^{a} f v = ^{\circ} f v }$ " and post'="{ True } " in Conseq) show " ${True} \cap {\hat{b} = 0} \subseteq {\hat{b} = 0}$ " by auto next show " $\{av = ov \land ab = ob \land afv = ofv\} \subseteq \{av = ov \land ab = ob$ $\wedge afv = ofv \}$ " by auto next show " $\{ ax = ax \lor ax = f ax = f x \} \subseteq \{ ax = ax \lor ax = f x \}$ " by auto \mathbf{next} show " ${True} \subseteq {True}$ " by auto next show " \vdash 'v := 'x;; 'fv := f 'v;; (IF 'x = 'v THEN 'x := 'fv;; b := 1 ELSE b := 0 FI sat $[\{ b = 0 \}, \{ av = ov \land ab = ob \land afv = ofv \},$ $\{ a_x = o_x \lor a_x = f \circ_x \}, \{ True \} \}''$ proof (rule_tac mid="{ $fv = f v }" in Seq$) show " \vdash 'v := 'x;; 'fv := f 'v sat [{'b = 0}, {av = $\circ v \land$ ${}^{a}b = {}^{o}b \wedge {}^{a}fv = {}^{o}fv$, $\{{}^{a}x = {}^{o}x \vee {}^{a}x = f {}^{o}x$, $\{{}^{f}v = f {}^{v}v$ } proof (rule_tac mid="{True}" in Seq) show " \vdash 'v := 'x sat [{ 'b = 0}, { av = $\circ v \land ab = \circ b \land afv$ $= {}^{\circ}fv$, $\{ {}^{a}x = {}^{\circ}x \lor {}^{a}x = f {}^{\circ}x \}$, $\{ True \}]"$ by (rule Basic, auto) \mathbf{next} show " \vdash fv := f v sat [{True}, { $av = ov \land ab = ob \land$ afv = ofv, $\{ax = ox \lor ax = f ox\}$, $\{fv = f v\}$ by (rule Basic, auto) qed next show " $\vdash \langle IF \ x = v \ THEN \ x := fv;; b := 1 \ ELSE \ b := 0$ FI sat [{ fv = f v}, { $av = v \wedge ab = b \wedge afv = ofv$ }, { $ax = v \vee v$ x = f x, {*True*}]" proof (rule Await,auto) show " $\bigwedge V$. \vdash IF 'x = 'v THEN 'x := 'fv;; 'b := Suc 0 ELSE `b := 0 FI sat [{`fv = f `v} \cap {V}, {(s, t). s = t}, UNIV, {`x = x V} $\vee x = f (x V)$ proof (rule Cond, auto) show " $\bigwedge V$. \vdash 'x := 'fv;; 'b := Suc 0 sat [{ 'fv = f 'v}] $\cap \{V\} \cap \{ x = v \}, \{(s, t). s = t\}, UNIV, \{ x = x V \lor x = f (x V) \}]"$ proof (rule_tac mid=" $\{ x = x V \lor x = f (x V) \}$ " in Seq) show " $\langle V$. \vdash 'x := 'fv sat [{'fv = f 'v} \cap {V} \cap {'x} = v, {(s, t). s = t}, UNIV, { $x = x V \lor x = f (x V)$ }]" by (rule Basic, auto) \mathbf{next}

```
show "\bigwedge V. \vdash 'b := Suc 0 sat [{ 'x = x V \lor 'x = f (x
by (rule Basic, auto)
             qed
           next
             show " \bigwedge V. \vdash 'b := 0 sat [{'fv = f 'v} \cap {V} \cap - {'x}]
= v, {(s, t). s = t}, UNIV, {[x = x V \vee x = f (x V)}]"
               by (rule Basic, auto)
           \mathbf{qed}
         \mathbf{qed}
       qed
     qed
   ged
 qed
qed
end
```

D Bibliography

References

- Atomic Ptr Plus. Available from World Wide Web: http:// atomic-ptr-plus.sourceforge.net/. This project is a collection of various lock-free synchronization primitives and fast pathed synchronization functions.
- [2] Generic Concurrent Lock-Free Linked List. Available from World Wide Web: http://www.cs.rpi.edu/~bushl2/project_web/page5.html.
- [3] NOBLE. Available from World Wide Web: http://www.cs.chalmers. se/~noble/.
- [4] Nonblocking multiprocessor/multithread algorithms in C++. Available from World Wide Web: http://www.musicdsp.org/archive. php?classid=0#148.
- [5] Software Transactional Memory. Available from World Wide Web: http://en.wikipedia.org/wiki/Software_transactional_memory.
- [6] J.-R. Abrial. The B-book: assigning programs to meanings. Cambridge University Press, New York, NY, USA, 1996.
- H. Gao. Design and verification of lock-free parallel algorithms. PhD thesis, Apr. 2005. Available from World Wide Web: http: //dissertations.ub.rug.nl/faculties/science/2005/h.gao/.

- [8] T. L. Harris, K. Fraser, and I. A. Pratt. A practical multi-word compare-and-swap operation. In *Proceedings of the 16th International Symposium on Distributed Computing*, 2002. Available from World Wide Web: http://www.cl.cam.ac.uk/research/srg/netos/ lock-free/.
- M. Herlihy. Wait-free synchronization. ACM Transactions on Programming Languages and Systems, 13(1):124-149, January 1991. Available from World Wide Web: http://citeseer.ist.psu.edu/ herlihy93waitfree.html.
- M. P. Herlihy and J. M. Wing. Linearizability: a correctness condition for concurrent objects. ACM Trans. Program. Lang. Syst., 12(3):463– 492, 1990. Available from World Wide Web: http://doi.acm.org/ 10.1145/78969.78972.
- [11] HP. Atomic Ops. Available from World Wide Web: http://www.hpl. hp.com/research/linux/atomic_ops/.
- [12] Keir Fraser, Tim Harris, Ian Pratt, and Chris Purcell. Practical lockfree data structures. Available from World Wide Web: http://www. cl.cam.ac.uk/research/srg/netos/lock-free/.
- [13] L. Lamport. The + CAL Algorithm Language. Available from World Wide Web: http://research.microsoft.com/users/ lamport/pubs/pubs.html#pluscal.
- [14] S. Owicki and D. Gries. Verifying properties of parallel programs: an axiomatic approach. Commun. ACM, 19(5):279-285, 1976. Available from World Wide Web: http://portal.acm.org/citation.cfm?id= 360051.360224.
- [15] L. Prensa Nieto. Verification of Parallel Programs with the Owicki-Gries and Rely-Guarantee Methods in Isabelle/HOL. PhD thesis, Technische Universität München, 2002. Available from World Wide Web: http://tumb1.biblio.tu-muenchen.de/publ/ diss/allgemein.html.
- [16] H. Sundell and P. Tsigas. Lock-free and practical deques using single-word compare-and-swap. Technical Report 2004-02, Computing Science, Chalmers University of Technology, Mar. 2004. Available from World Wide Web: http://citeseer.ist.psu.edu/ sundell04lockfree.html.
- [17] V. Vafeiadis, M. Herlihy, T. Hoare, and M. Shapiro. Proving correctness of highly-concurrent linearisable objects. In *PPoPP '06: Proceedings* of the eleventh ACM SIGPLAN symposium on Principles and practice

of parallel programming, pages 129–136, New York, NY, USA, 2006. ACM Press. Available from World Wide Web: http://doi.acm.org/10.1145/1122971.1122992.